

Mar 04 2017 04:02:06-PM

VIN: KMHHXXDX3UXXXXXX

Mode 6 Information:

- Rich to lean sensor threshold voltage (constant), x, Status: Test Fail TID: 01 ID: 01 MIN: - VAL: 0x27 MAX 0x13
- Lean to rich sensor threshold voltage (constant), ✓, Status: Complete and Pass TID: 02 ID: 01 MIN: - VAL: 0x00 MAX 0x40
- Lean to rich sensor threshold voltage (constant), ✓, Status: Complete and Pass TID: 02 ID: 03 MIN: - VAL: 0x00 MAX 0x40
- Lean to rich sensor threshold voltage (constant), ✓, Status: Complete and Pass TID: 02 ID: 05 MIN: 0x6D VAL: 0x80 MAX -
- Lean to rich sensor threshold voltage (constant), ✓, Status: Complete and Pass TID: 02 ID: 05 MIN: - VAL: 0x80 MAX 0x93
- Lean to rich sensor threshold voltage (constant), ✓, Status: Complete and Pass TID: 02 ID: 07 MIN: - VAL: 0x8000 MAX 0xFFFF
- Lean to rich sensor threshold voltage (constant), ✓, Status: Complete and Pass TID: 02 ID: 09 MIN: - VAL: 0x08 MAX 0x40
- Lean to rich sensor threshold voltage (constant), ✓, Status: Complete and Pass TID: 02 ID: 0B MIN: - VAL: 0x12 MAX 0x40
- Lean to rich sensor threshold voltage (constant), ✓, Status: Complete and Pass TID: 02 ID: 0D MIN: 0x6D VAL: 0x76 MAX -
- Lean to rich sensor threshold voltage (constant), ✓, Status: Complete and Pass TID: 02 ID: 0D MIN: - VAL: 0x76 MAX 0x93
- Rich to lean sensor switch time (calculated), ✓, Status: Complete and Pass TID: 05 ID: 02 MIN: - VAL: 0x00 MAX 0x1A

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- Rich to lean sensor switch time (calculated), ✓, Status: Complete and Pass
TID: 05 ID: 03 MIN: - VAL: 0x00 MAX 0x2D
 - Rich to lean sensor switch time (calculated), ✓, Status: Complete and Pass
TID: 05 ID: 09 MIN: - VAL: 0x5082 MAX 0x5120
 - Rich to lean sensor switch time (calculated), ✓, Status: Complete and Pass
TID: 05 ID: 0A MIN: 0x79C0 VAL: 0x8104 MAX -
 - Rich to lean sensor switch time (calculated), ✓, Status: Complete and Pass
TID: 05 ID: 10 MIN: - VAL: 0x8082 MAX 0x8190
 - Time between sensor transitions (calculated), ✓, Status: Complete and Pass
TID: 09 ID: 01 MIN: 0xA3 VAL: 0xB2 MAX -
 - EWMA (Exponential Weighted Moving Average) misfire counts for last ten (10) driving cycles (calculated, rounded to an integer value), ✓, Status: Complete and Pass
TID: 0B ID: 01 MIN: - VAL: 0x00 MAX 0x28
 - Misfire counts for last/current driving cycles (calculated, rounded to an integer value), ✓, Status: Complete and Pass
TID: 0C ID: 01 MIN: - VAL: 0x00 MAX 0x28
 - Reserved for future standardization, ✓, Status: Complete and Pass
TID: 0D ID: 01 MIN: - VAL: 0x02 MAX 0x4B0
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Vehicle Protocol: KWP2000_Fast

Sensor F/W Version: v2.35

App Version: 6.8.0-b83

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